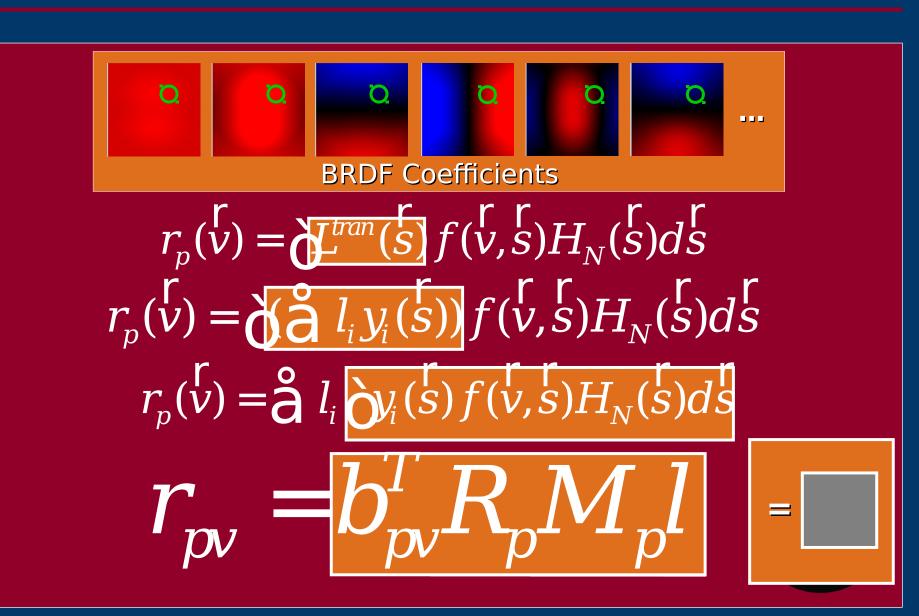
Arbitrary BRDFs [Kautz02]





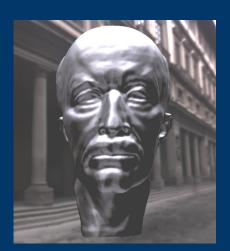
Arbitrary BRDF Results







Anisotropic BRDFs





Other BRDFs



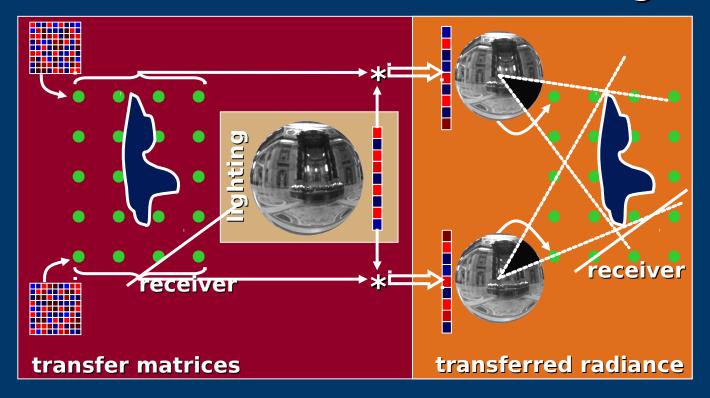


Spatially Varying

Neighborhood Transfer



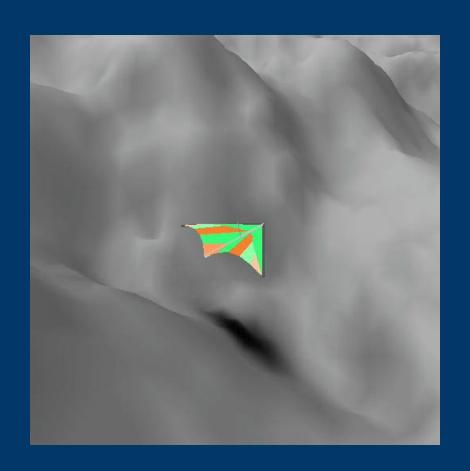
- Allows to cast shadows/caustics onto arbitrary receivers
- Store how object scatters/blocks light around itself (transfer matrices on grid)



Neighborhood Transfer Results

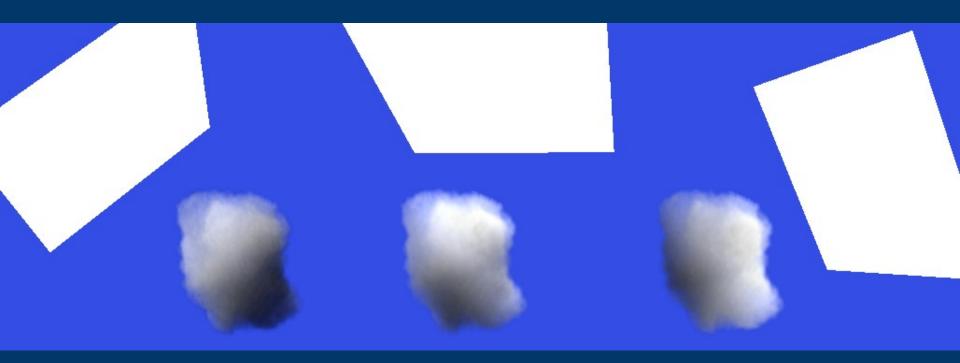


- 64x64x8 neighborhood
- diffuse receiver
- timings on 2.2Ghz P4, ATI Radeon 8500
- 4fps if light changes
- 120fps for constant light



Volumes





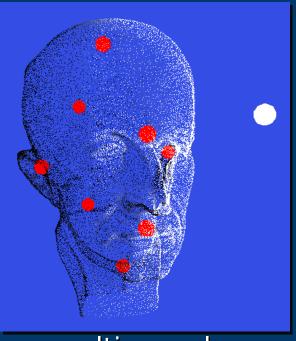
- Diffuse volume: 32x32x32 grid
- Runs at 40fps on 2.2Ghz P4, ATI 8500
- Here: dynamic lighting

Local Lighting using Radiance Sampling





single sample (at center = light at ∞)



multi-sample locations

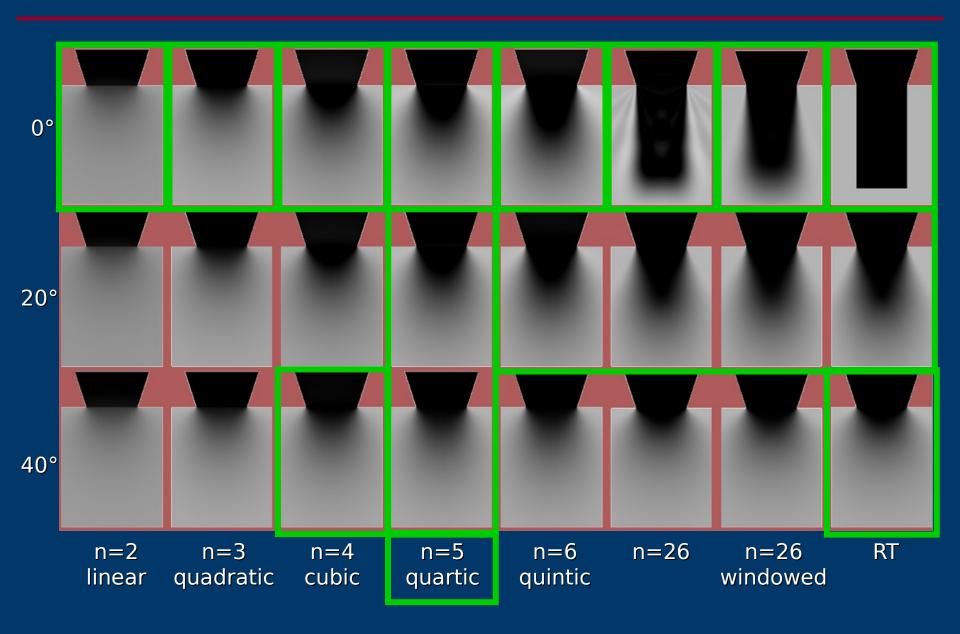


multi-sample result

- Sample incident radiance at multiple points
- Choose sample points over object using ICP from VQ
- Correct for shadows but not interreflections

Light Size vs. SH Order





Results



Live Demo

Conclusions



Pros:

- Fast, arbitrary dynamic lighting
 - on surfaces or in volumes
- Includes shadows and interreflections
- Works for diffuse and glossy BRDFs

Cons:

- Works only for low-frequency lighting
- Rigid objects only, no deformation

Future Work



- Practical glossy transfer
 - Eliminate frozen view/light constraints
 - Compress matrices/vectors
- Enhanced preprocessing
 - Subsurface scattering, dispersion
 - Simulator optimization
 - Adaptive sampling of transfer over surface
- Deformable objects

Acknowledgements



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 - Jason Mitchell & Michael Doggett (ATI)
 - Matthew Papakipos (NVidia)
 - Paul Debevec for light probes
 - Stanford Graphics Lab for Buddha model
 - Michael Cohen, Chas Boyd, Hans-Peter Seidel for early discussions and support

Questions?

Performance



Model	# Verts	GF4 4600	R300	Pre-	
		FPS	FPS	compute	
Max	50,060	215	304	1.1h	
Buddha	49,990	191	269	2.5h	
Tweety	48,668	240	326	1.2h	
Tyra	100,000	118	179	2.4h	
Teapot	152,413	93	154	4.4h	

Matrix Formulation



$$M_i = \mathcal{L}(s)B_i(s)V(s)ds$$

$$M_i = \partial \hat{\mathbf{a}} l_j B_j(\hat{s}) B_i(\hat{s}) V(\hat{s}) d\hat{s}$$

$$M_i = \mathring{\mathbf{a}} l_j \mathring{\mathbf{b}}_j(s) B_i(s) V(s) ds$$

$$M_{ij} = \partial B_i(s)B_j(s)V(s)ds$$

Results - Preprocessing

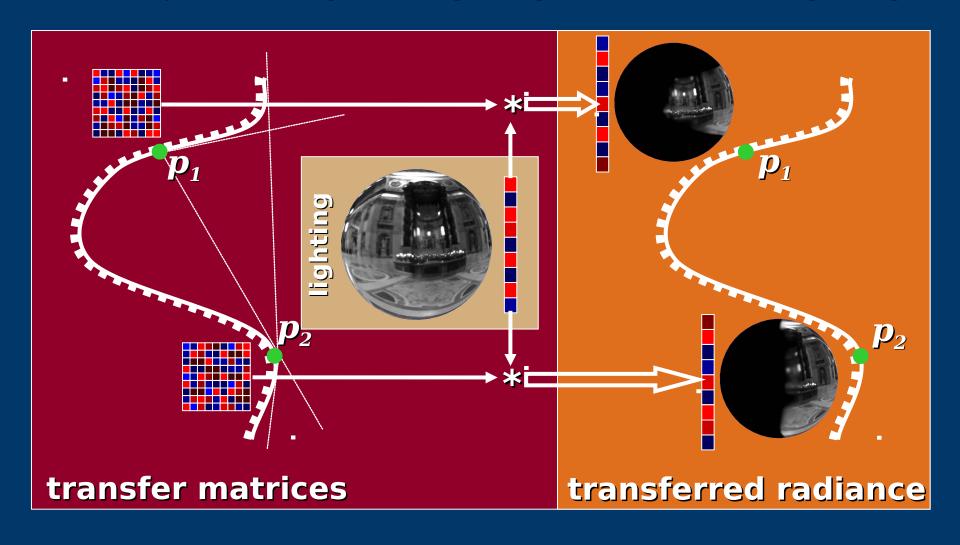


Model	Туре	Sampling	Preproc.	FPS
head	diffuse	50K vert.	1.1h	129
ring	diffuse	256x256 t.	8m	94
buddha	diffuse	50K vert.	2.5h	125
buddha	glossy	50K vert.	2.5h	125
tyra	diffuse	100K vert.	2.4h	83
tyra	glossy	100K vert.	2.4h	83
teapot	glossy	150K vert.	4.4h	49
cloud	diffuse	32x32x32	15m	40
glider	neighb.	64x64x8	3h	120

Transfer Matrix



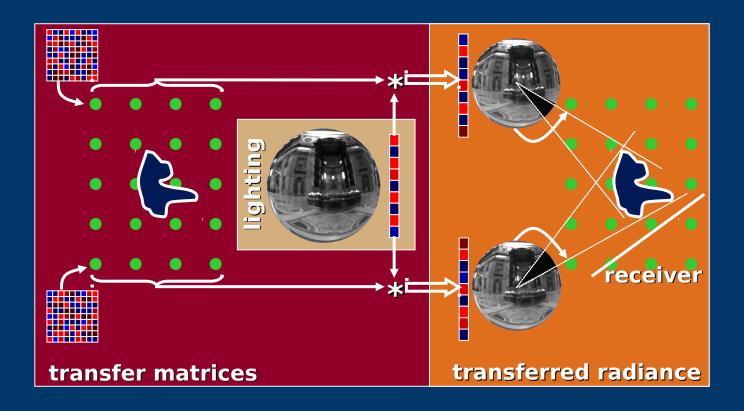
Precompute how global lighting ⇒ transferred lighting



Neighborhood Transfer



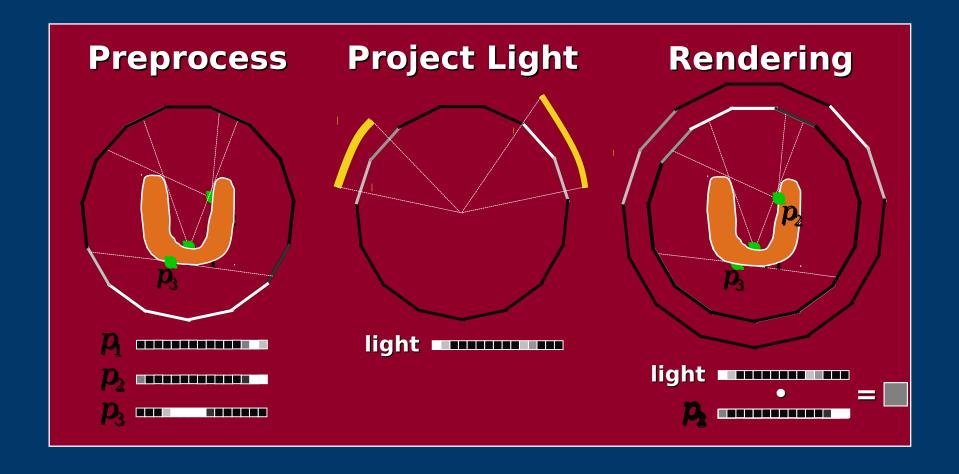
- Store how object transfers radiance around itself
- Transfer matrices on grid



Diffuse Self-Transfer



2D example, piecewise constant basis, shadows only



Previous Work - Precomputed Transport

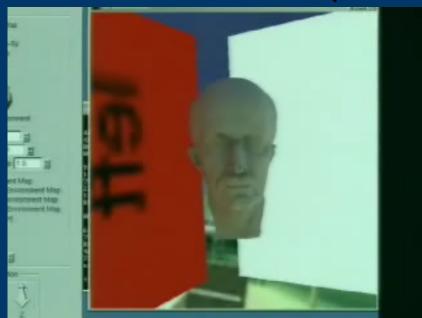


- [Greger96] irradiance volumes move diffuse object through precomputed lighting
- [Miller98, Wood00, Chen02] surface lightfields frozen lighting environments
- [Ashikmin02] steerable illumination textures steers small light source over diffuse object
- [Matusik02] image-based 3D photography surface lightfield + reflectance field - not interactive

Dynamic Lighting



Sample incident lighting Lon-the-fly



- Results
 - low-resolution cube maps sufficient: 6x16x16
 - average error: 0.2%, worst-case: 0.5%
 - takes 1.16 ms on P3-933Mhz, ATI 8500